

Stochastic Local Volatility in QuantLib

J. Göttker-Schnetmann, K. Spanderen

QuantLib User Meeting 2014
Düsseldorf
2014-12-06

- Heston Stochastic Local Volatility

- Fokker-Planck Equations
 - Square Root Process
 - Boundary Conditions
 - Coordinate and Density Transformations

- Calibration

Local Volatility [Dupire 1994]

- Local Volatility $\sigma_{LV}(\mathbf{S}, t)$ as function of spot level S_t and time t :

$$d \ln S_t = \left(r_t - q_t - \frac{1}{2} \sigma_{LV}^2(\mathbf{S}, t) \right) dt + \sigma_{LV}(\mathbf{S}, t) dW_t$$
$$\sigma_{LV}^2(\mathbf{S}, t) = \frac{\frac{\partial C}{\partial T} + (r_t - q_t) K \frac{\partial C}{\partial K} + q_t C}{\frac{K^2}{2} \frac{\partial^2 C}{\partial K^2}} \Bigg|_{K=S, T=t}$$

- Consistent with option market prices.
- Model is often criticized for its unrealistic volatility dynamics.
- Dupire formula is mathematically appealing but also unstable.

Stochastic Volatility [Heston 1993]

- Stochastic volatility given by a square-root process:

$$\begin{aligned}d \ln S_t &= \left(r_t - q_t - \frac{1}{2} \nu_t \right) dt + \sqrt{\nu_t} dW_t^S \\d \nu_t &= \kappa (\theta - \nu_t) dt + \sigma \sqrt{\nu_t} dW_t^\nu \\ \rho dt &= dW_t^\nu dW_t^S\end{aligned}$$

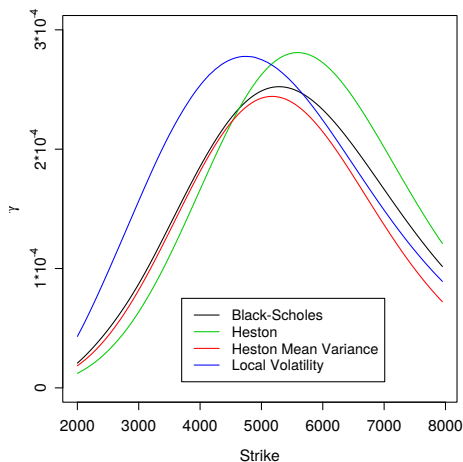
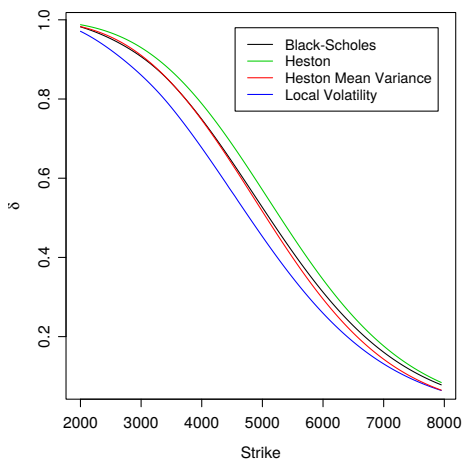
- Semi-analytical solution for European call option prices:

$$\begin{aligned}C(S_0, K, \nu_0, T) &= SP_1 - Ke^{-(r_t - q_t)T} P_2 \\ P_j &= \frac{1}{2} + \frac{1}{\pi} \int_0^\infty \Re \left[\frac{e^{-iu \ln K} \phi_j(S_0, K, \nu_0, T, u)}{iu} \right] du\end{aligned}$$

- More realistic volatility dynamics.
- Does often not exhibit enough skew for short dated expiries.

Example: Differences in δ and γ

The implied and local volatility surface is derived from the Heston model and therefore the option prices between all models match. $S_0 = 5000, \kappa = 5.66, \theta = 0.075, \sigma = 1.16, \rho = -0.51, \nu_0 = 0.19, T = 1.7$



- Add leverage function $L(S_t, t)$ and mixing factor η :

$$\begin{aligned}d \ln S_t &= \left(r_t - q_t - \frac{1}{2} L(S_t, t)^2 \nu_t \right) dt + L(S_t, t) \sqrt{\nu_t} dW_t^S \\d \nu_t &= \kappa (\theta - \nu_t) dt + \eta \sigma \sqrt{\nu_t} dW_t^\nu \\ \rho dt &= dW_t^\nu dW_t^S\end{aligned}$$

- Leverage $L(x_t, t)$ is given by probability density $p(S_t, \nu, t)$ and

$$L(S_t, t) = \frac{\sigma_{LV}(S_t, t)}{\sqrt{\mathbb{E}[\nu_t | S = S_t]}} = \sigma_{LV}(S_t, t) \sqrt{\frac{\int_{\mathbb{R}^+} p(S_t, \nu, t) d\nu}{\int_{\mathbb{R}^+} \nu p(S_t, \nu, t) d\nu}}$$

- Mixing factor η tunes between stochastic and local volatility.

Cheat Sheet: Link between SDE and PDE

Starting point is a multidimensional SDE of the form:

$$d\mathbf{x}_t = \boldsymbol{\mu}(\mathbf{x}_t, t)dt + \boldsymbol{\sigma}(\mathbf{x}_t, t)d\mathbf{W}_t$$

Feynman-Kac: price of a derivative $u(\mathbf{x}_t, t)$ with boundary condition $u(\mathbf{x}_T, T)$ at maturity T is given by:

$$\partial_t u + \sum_{k=1}^n \mu_k \partial_{x_k} u + \frac{1}{2} \sum_{k,l=1}^n (\boldsymbol{\sigma} \boldsymbol{\sigma}^T)_{kl} \partial_{x_k} \partial_{x_l} u - ru = 0$$

Fokker-Planck: time evolution of the probability density function $p(\mathbf{x}_t, t)$ with the initial condition $p(\mathbf{x}, t=0) = \delta(\mathbf{x} - \mathbf{x}_0)$ is given by:

$$\partial_t p = - \sum_{k=1}^n \partial_{x_k} [\mu_k p] + \frac{1}{2} \sum_{k,l=1}^n \partial_{x_k} \partial_{x_l} \left[(\boldsymbol{\sigma} \boldsymbol{\sigma}^T)_{kl} p \right]$$

Backward Feynman-Kac Equation

The SLV model leads to following Feynman-Kac equation for a function $u : \mathbb{R} \times \mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$, $(x, \nu, t) \mapsto u(x, \nu, t)$:

$$0 = \partial_t u + \frac{1}{2} L^2 \nu \partial_x^2 u + \frac{1}{2} \eta^2 \sigma^2 \nu \partial_\nu^2 u + \eta \sigma \nu \rho L \partial_x \partial_\nu u \\ + \left(r - q - \frac{1}{2} L^2 \nu \right) \partial_x u + \kappa (\theta - \nu) \partial_\nu u - ru$$

- PDE can be solved using either Implicit scheme (slow) or more advanced [operator splitting schemes](#) like modified Craig-Sneyd or Hundsdorfer-Verwer in conjunction with damping steps (fast).
- Implementation is mostly harmless, extend `FdmHestonOp`.

Forward Fokker-Planck Equation

The corresponding Fokker-Planck equation for the probability density $\rho : \mathbb{R} \times \mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$, $(x, \nu, t) \mapsto \rho(x, \nu, t)$ is:

$$\begin{aligned} \partial_t \rho &= \frac{1}{2} \partial_x^2 [L^2 \nu \rho] + \frac{1}{2} \eta^2 \sigma^2 \partial_\nu^2 [\nu \rho] + \eta \sigma \rho \partial_x \partial_\nu [L \nu \rho] \\ &\quad - \partial_x \left[\left(r - q - \frac{1}{2} L^2 \nu \right) \rho \right] - \partial_\nu [\kappa (\theta - \nu) \rho] \end{aligned}$$

- Numerical solution of the PDE is cumbersome due to difficult boundary conditions and the Dirac delta distribution as the initial condition.
- PDE can be efficiently solved using operator splitting schemes, preferable the modified Craig-Sneyd scheme

Square Root Process

Main issues of the implementation are caused by the square root process:

$$d\nu_t = \kappa(\theta - \nu_t)dt + \sigma\sqrt{\nu_t}dW$$

It has the following Fokker-Planck equation for the probability density $p : \mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$, $(\nu, t) \mapsto p(\nu, t)$:

$$\partial_t p = \frac{\sigma^2}{2} \partial_\nu^2 [\nu p] - \partial_\nu [\kappa(\theta - \nu)p]$$

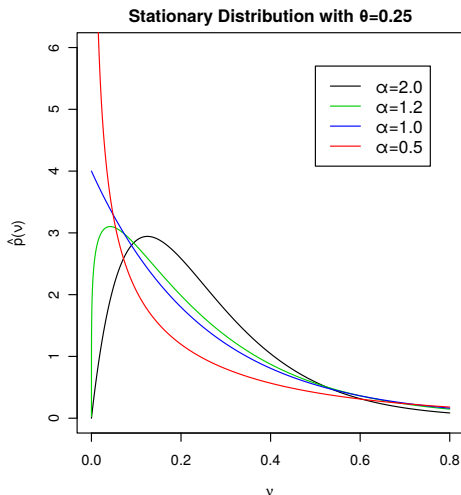
The stationary probability density $\hat{p}(\nu)$ with $\partial_t \hat{p}(\nu) = 0$ is:

$$\hat{p}(\nu) = \beta^\alpha \nu^{\alpha-1} \exp(-\beta\nu) \Gamma(\alpha)^{-1}, \alpha = \frac{2\kappa\theta}{\sigma^2}, \beta = \frac{\alpha}{\theta}$$

Stationary Probability Density

$$\lim_{\nu \rightarrow 0} \hat{p}(\nu) = \begin{cases} \infty & \text{if } \alpha < 1 \\ \theta^{-1} & \text{if } \alpha = 1 \\ 0 & \text{if } \alpha > 1 \end{cases}$$

The square root process ν_t is strictly positive if the **Feller Condition** $\alpha > 1$ is met.



Boundary Condition

The probability weight within $[\nu_{min}, \nu_{max}]$ of $p(\nu, t)$ is evolving by:

$$\partial_t \int_{\nu_{min}}^{\nu_{max}} d\nu p = \int_{\nu_{min}}^{\nu_{max}} d\nu \left(\frac{\sigma^2}{2} \partial_\nu^2 [\nu p] - \partial_\nu [\kappa(\theta - \nu)p] \right)$$

In order to avoid leaking of probability we enforce:

$$\begin{aligned} \partial_t \int_{\nu_{min}}^{\nu_{max}} d\nu p = 0 &\Rightarrow \left[\frac{\sigma^2}{2} \partial_\nu [\nu p] - [\kappa(\theta - \nu)p] \right] \Big|_{\nu_{min}}^{\nu_{max}} = 0 \\ &\Rightarrow \left[\frac{\sigma^2}{2} \partial_\nu [\nu p] - [\kappa(\theta - \nu)p] \right] \Big|_{\nu=\nu_{min}, \nu_{max}} = 0 \end{aligned}$$

Zero Flux Boundary Condition

On a non-uniform grid $\{z_1, \dots, z_n\}$ the two-sided approximation of $\partial_z f$ is:

$$\begin{aligned}\partial_z f(z_i) &\approx \frac{h_{i-1}^2 f_{i+1} + (h_i^2 - h_{i-1}^2) f_i - h_i^2 f_{i-1}}{h_{i-1} h_i (h_{i-1} + h_i)} \\ &= \frac{h_{i-1}}{h_{i-1} + h_i} \frac{f_{i+1} - f_i}{h_i} + \frac{h_i}{h_{i-1} + h_i} \frac{f_i - f_{i-1}}{h_{i-1}}\end{aligned}$$

With $h_i := z_{i+1} - z_i$ and $f_i := f(z_i)$. The second order derivative is approximated by:

$$\partial_z^2 f(z_i) \approx \frac{h_{i-1} f_{i+1} - (h_{i-1} + h_i) f_i + h_i f_{i-1}}{\frac{1}{2} h_{i-1} h_i (h_{i-1} + h_i)}$$

Sort by factors of f_i , set

$$\begin{aligned}\zeta_i &:= h_i h_{i-1} \\ \zeta_i^p &:= h_i (h_{i-1} + h_i) \\ \zeta_i^m &:= h_{i-1} (h_{i-1} + h_i)\end{aligned}$$

then:

$$\begin{aligned}\partial_z f(z_i) &\approx \frac{h_{i-1}}{\zeta_i^p} f_{i+1} + \frac{(h_i - h_{i-1})}{\zeta_i} f_i - \frac{h_i}{\zeta_i^m} f_{i-1} \\ \partial_z^2 f(z_i) &\approx \frac{2}{\zeta_i^p} f_{i+1} - \frac{2}{\zeta_i} f_i + \frac{2}{\zeta_i^m} f_{i-1}\end{aligned}$$

A general partial differential equation of the form

$$\partial_t f = A(z)\partial_z^2 f + B(z)\partial_z f + C(z)f$$

has therefore the spacial discretization:

$$\begin{aligned}\partial_t f(z_i) &= \frac{2A_i + B_i h_{i-1}}{\zeta_i^p} f_{i+1} + \left(\frac{-2A_i + B_i(h_i - h_{i-1})}{\zeta_i} + C_i \right) f_i \\ &\quad + \frac{2A_i - B_i h_i}{\zeta_i^m} f_{i-1} \\ &=: \gamma_i f_{i+1} + \beta_i f_i + \alpha_i f_{i-1}\end{aligned}$$

Discretization

This is interpreted as a tridiagonal transfer matrix T with diagonal β_i , upper diagonal γ_i , and lower diagonal α_j :

$$T := \begin{pmatrix} \beta_1 & \gamma_1 & 0 & \dots & & \\ \alpha_2 & \beta_2 & \gamma_2 & 0 & \dots & \\ 0 & \alpha_3 & \beta_3 & \gamma_3 & 0 & \dots \\ \vdots & 0 & \ddots & \ddots & \ddots & 0 \\ & \vdots & & \alpha_{n-1} & \beta_{n-1} & \gamma_{n-1} \\ & & & & \alpha_n & \beta_n \end{pmatrix}$$

Then

$$\partial_t \begin{pmatrix} f_1 \\ \vdots \\ f_n \end{pmatrix} = T \begin{pmatrix} f_1 \\ \vdots \\ f_n \end{pmatrix}$$

Boundary Condition

Add z_0 below the lower boundary and z_{n+1} above the upper boundary to the grid. The zero flux condition takes the general form

$$[\partial_z A(z, t)f + B(z, t)f] \Big|_{z=z_0, z_{n+1}} \stackrel{!}{=} 0$$

Lower Boundary: The partial derivative is discretized by a second order forward differentiation, so that all terms are given by grid points

$$\begin{aligned} \partial_z f(z_0) &\approx \frac{-h_0^2 f_2 + (h_1 + h_0)^2 f_1 - ((h_1 + h_0)^2 - h_0^2) f_0}{h_0 h_1 (h_1 + h_0)} \\ &= -\frac{h_0}{\zeta_1^p} f_2 + \frac{(h_0 + h_1)}{\zeta_1} f_1 - \frac{(2h_0 + h_1)}{\zeta_1^m} f_0 \end{aligned}$$

Boundary Condition

The general zero-flux boundary condition is therefore discretized at the lower boundary as

$$\begin{aligned}0 &= -\frac{h_0}{\zeta_1^p} A_0 f_2 + \frac{(h_0 + h_1)}{\zeta_1} A_0 f_1 + \left(-\frac{(2h_0 + h_1)}{\zeta_1^m} A_0 + B_0 \right) f_0 \\ &=: c_1 f_2 + b_1 f_1 + a_1 f_0 \\ \Rightarrow f_0 &= -\frac{c_1}{a_1} f_2 - \frac{b_1}{a_1} f_1\end{aligned}$$

$$\begin{aligned}\partial_t f_1 &= \gamma_1 f_2 + \beta_1 f_1 + \alpha_1 f_0 \\ &= \left(\gamma_1 - \alpha_1 \frac{c_1}{a_1} \right) f_2 + \left(\beta_1 - \alpha_1 \frac{b_1}{a_1} \right) f_1\end{aligned}$$

→ modification of the transfer matrix.

Non-Uniform Meshes

Non-uniform meshes are a key component [Tavella & Randall 2000]

Define coordinate transformation

$Y = Y(\epsilon)$ for n critical points B_k with density factors β_k

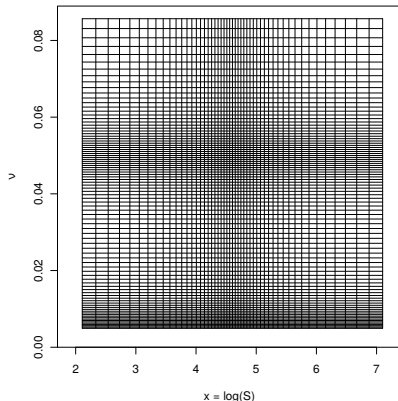
$$\frac{dY(\epsilon)}{d\epsilon} = A \left[\sum_{k=1}^n J_k(\epsilon)^{-2} \right]^{-\frac{1}{2}}$$

$$J_k(\epsilon) = \sqrt{\beta^2 + (Y(\epsilon) - B_k)^2}$$

$$Y(0) = Y_{min}$$

$$Y(1) = Y_{max}$$

ODE solver is based on Peter's Runge-Kutta implementation.



Example: $x_0 = \ln(100)$, $\nu_0 = 0.05$,
Feller constraint is fulfilled

Loss of Probability

Time evolution of the stationary distribution with zero flux condition.

$$P(x) = \int_{-\infty}^x \hat{p}(\nu) d\nu$$

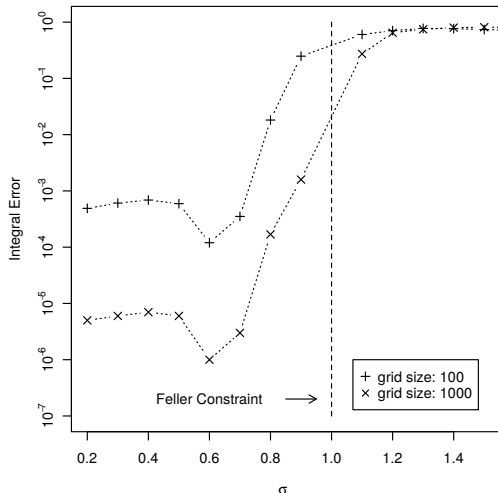
$$\nu_{min} = P^{-1}(0.01)$$

$$\nu_{max} = P^{-1}(0.99)$$

$$\int_{\nu_{min}}^{\nu_{max}} \hat{p} d\nu = 0.98$$

Integral error after evolving
for one year:

$$\left| \int_{\nu_{min}}^{\nu_{max}} \rho(\nu, t = 1y) d\nu - 0.98 \right|$$



Recap: Stationary distribution:

$$\hat{p}(\nu) = \beta^\alpha \nu^{\alpha-1} \exp(-\beta\nu) \Gamma(\alpha)^{-1}$$

Remove divergence following Lucic [2] by using

$$\begin{aligned} q &= \nu^{1-\alpha} p \\ \Rightarrow \partial_t q &= \frac{\sigma^2}{2} \nu \partial_\nu^2 q + \kappa(\nu + \theta) \partial_\nu q + \frac{2\kappa^2 \theta}{\sigma^2} q \end{aligned}$$

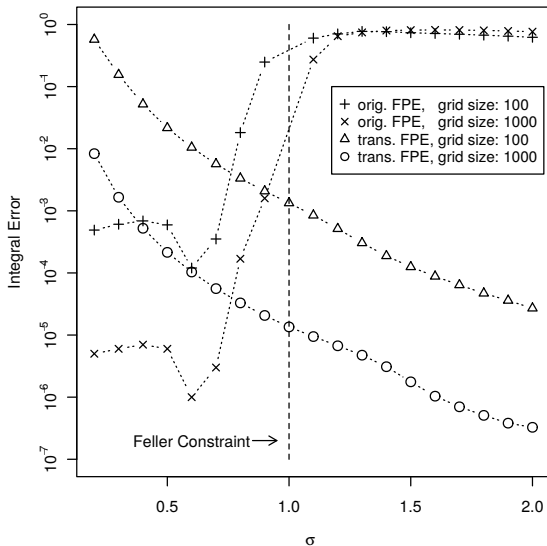
This equation has the stationary solution

$$\hat{q}(\nu) = \beta^\alpha \exp(-\beta\nu) \Gamma(\alpha)^{-1}$$

which converges to $\beta^\alpha \Gamma(\alpha)^{-1}$ as $\nu \rightarrow 0$

Transformed Probability Density

Time evolution of the transformed distribution with zero flux condition.



Apply Itô's lemma to $z = \log \nu$:

$$dz = \left((\kappa\theta - \frac{\sigma^2}{2}) \frac{1}{\nu} - \kappa \right) dt + \sigma \frac{1}{\sqrt{\nu}} dW$$

Fokker-Planck equation for the probability distribution

$f : \mathbb{R} \times \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$, $(z, t) \mapsto f(z, t)$ ($\nu = \exp(z)$):

$$\partial_t f(z, t) = -\partial_z \left((\kappa\theta - \frac{\sigma^2}{2}) \frac{1}{\nu} - \kappa \right) f + \partial_z^2 \left(\frac{\sigma^2}{2} \frac{1}{\nu} f \right)$$

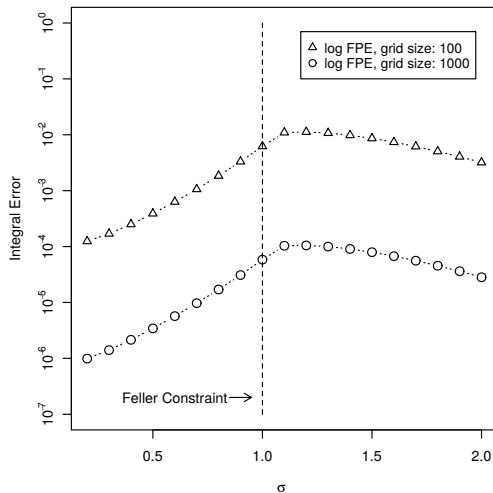
Stationary solution:

$$\hat{f}(z) = \beta^\alpha \exp(z\alpha) \exp(-\beta \exp(z)) \Gamma(\alpha)^{-1} = \nu \hat{p}(\nu)$$

\hat{f} converges to 0 as $z \rightarrow -\infty$

Log Coordinates

Time evolution of log probability density with zero flux condition



$$\nu_{min} = \min(0.001, F^{-1}(0.01))$$

- Proper implementation of the zero flux boundary condition is not enough to get a stable scheme.
 - Transformation of the PDE in log coordinates leads to a less poisonous problem.
 - Non-Uniform meshers are a key component for success.
- all in all, mostly harmless 😊. Time for another dimension

Zero Flux Boundary Condition in two Dimensions

Adding the stock process to the picture complicates matters a bit. Probability density has a second variable $x = \log S$, and the Fokker-Planck equation reads

$$\partial_t f = \partial_z^2 A(z, x, t)f + \partial_z B(z, x, t)f + \partial_z \partial_x \rho C(z, x, t)f + \text{powers of } \partial_x$$

Stretching the argument above a bit¹ we arrive at the boundary condition

$$[\partial_z A(z, x, t)f + B(z, x, t)f + \rho \partial_x C(z, x, t)f] \Big|_{z=z_0, z_1} \stackrel{!}{=} 0$$

¹Can be made rigorous [2]

$$\begin{aligned}dx_t &= \left(r_t - q_t - \frac{\nu_t}{2}\right)dt + \sqrt{\nu_t}L(x, t)dW_t^x \\d\nu_t &= \kappa(\theta - \nu_t)dt + \eta\sigma\sqrt{\nu_t}dW_t^\nu \\ \rho dt &= dW_t^x dW_t^\nu\end{aligned}$$

Fokker-Planck equation:

$$\begin{aligned}\partial_t p &= \frac{1}{2}\partial_x^2 [L^2 \nu p] + \frac{1}{2}\eta^2 \sigma^2 \partial_\nu^2 [\nu p] + \eta\sigma\rho\partial_x\partial_\nu [L\nu p] \\ &\quad - \partial_x \left[\left(r - q - \frac{1}{2}L^2\nu \right) p \right] - \partial_\nu [\kappa(\theta - \nu) p]\end{aligned}$$

The zero flux condition takes the form $\forall x$:

$$\left[\frac{\sigma^2}{2}\nu\partial_\nu p + \left(\kappa(\nu - \theta) + \frac{\sigma^2}{2} \right) p + \rho\nu\sigma\partial_x Lp \right] \Big|_{\nu=\nu_0, \nu=\nu_{n+1}} = 0$$

Fokker-Planck equation for $q = v^{1-\alpha} p$

$$\begin{aligned} \partial_t q &= \frac{\nu}{2} \partial_x^2 L^2 q + (-r_t + q_t) \partial_x q + \partial_x \left(\frac{\nu}{2} L^2 + \rho \sigma \frac{2\kappa\theta}{\sigma^2} L \right) q \\ &\quad + \frac{\sigma^2}{2} \nu \partial_\nu^2 q + \kappa(\nu + \theta) \partial_\nu q + \frac{2\kappa^2\theta}{\sigma^2} q \\ &\quad + \rho \sigma \nu \partial_x \partial_\nu L q \end{aligned}$$

The zero flux condition takes the form $\forall x$:

$$\left[\frac{\sigma^2}{2} \nu \partial_\nu q + \kappa \nu q + \rho \nu \sigma \partial_x L q \right] \Big|_{\nu=\nu_0, \nu=\nu_{n+1}} = 0$$

$$\begin{aligned}
 dx_t &= \left(r_t - q_t - \frac{\nu_t}{2}\right)dt + \sqrt{\nu_t}L(x, t)dW_t^x \\
 dz_t &= \left(\left(\kappa\theta - \frac{\sigma^2}{2}\right)\frac{1}{\nu} - \kappa\right)dt + \eta\sigma\frac{1}{\sqrt{\nu}}dW_t^\nu \\
 \rho dt &= dW_t^x dW_t^\nu
 \end{aligned}$$

Fokker-Planck equation:

$$\begin{aligned}
 \partial_t f &= \frac{1}{2}\partial_x^2 \left[L^2 \nu f\right] + \frac{\eta^2 \sigma^2}{2}\partial_z^2 \left[\frac{1}{\nu} f\right] + \eta\sigma\rho\partial_x\partial_z [Lf] \\
 &\quad - \partial_x \left[\left(r - q - \frac{1}{2}L^2\nu\right) f\right] - \partial_z \left[\left(\left(\kappa\theta - \frac{\sigma^2}{2}\right)\frac{1}{\nu} - \kappa\right) f\right]
 \end{aligned}$$

The zero-flux boundary condition is

$$\left[\frac{\eta^2 \sigma^2}{2}\frac{1}{\nu}\partial_z f - \kappa\left(1 - \frac{\theta}{\nu}\right)f + \rho\sigma\partial_x Lf\right] \Big|_{\nu=\nu_0, \nu=\nu_{n+1}} \stackrel{!}{=} 0$$

Example log coordinates:

$$\begin{aligned}\partial_t f &= \frac{1}{2} \partial_x^2 [L^2 \nu f] + \frac{\eta^2 \sigma^2}{2} \partial_z^2 \left[\frac{1}{\nu} f \right] + \eta \sigma \rho \partial_x \partial_z [L f] \\ &\quad - \partial_x \left[\left(r - q - \frac{1}{2} L^2 \nu \right) f \right] - \partial_z \left[\left(\kappa \theta - \frac{\sigma^2}{2} \right) \frac{1}{\nu} - \kappa \right] f\end{aligned}$$

$$\begin{aligned}\partial_t f &= \frac{\nu}{2} \partial_x^2 L^2 f + \frac{\eta^2 \sigma^2}{2} \frac{1}{\nu} \partial_z^2 f + \eta \sigma \rho \partial_x \partial_z L f \\ &\quad + (-r + q) \partial_x f + \frac{\nu}{2} \partial_x L^2 f + \left[\left(-\kappa \theta - \frac{\sigma^2}{2} \right) \frac{1}{\nu} + \kappa \right] \partial_z f + \frac{\kappa \theta}{\nu} f\end{aligned}$$

Use multiplication of derivative operators with L on the right hand side, added method `multR` to `TripleBandBinearOp` (saves some terms).

Start Condition: Dirac Delta Distribution

To begin with the Dirac delta distribution need to be regularized.

Approximation for small Δt based on

$$L(x, t) = \frac{\sigma_{LV}(x_{t=0}, 0)}{\sqrt{\nu_0}} = \text{const} \forall t \in [0, \Delta t]$$

- 1 Exact solution is known for $\rho = 0$
- 2 One Euler Step based on the SDE leads to bivariate Gaussian distribution
- 3 Semi-Analytical solution for exact sampling [Brodie, Kaya 2006]

- Start with a calibrated Local Volatility Model $\sigma_{LV}(x_t, t)$ and calibrated Heston Model $(\nu_0, \theta, \kappa, \sigma, \rho)$
- Recap: Leverage $L(x_t, t)$ is given by

$$L(x_t, t) = \frac{\sigma_{LV}(x_t, t)}{\sqrt{\mathbb{E}[\nu_t | X = x_t]}} = \sigma_{LV}(x_t, t) \sqrt{\frac{\int_{\mathbb{R}^+} \rho(x_t, \nu, t) d\nu}{\int_{\mathbb{R}^+} \nu \rho(x_t, \nu, t) d\nu}}$$

- Start condition: $p(x, \nu, 0) = \delta(x - x_0)\delta(\nu - \nu_0)$

$$\Rightarrow L(x_{t=0}, 0) = \frac{\sigma_{LV}(x_{t=0}, 0)}{\sqrt{\nu_0}}$$

Iterative Scheme:

- 1 Use Fokker-Planck equation to get from

$$p(x, \nu, t) \rightarrow p(x, \nu, t + \Delta t)$$

assuming a piecewise constant leverage function $L(x_t, t)$ in t

- 2 Calculate leverage function at $t + \Delta t$:

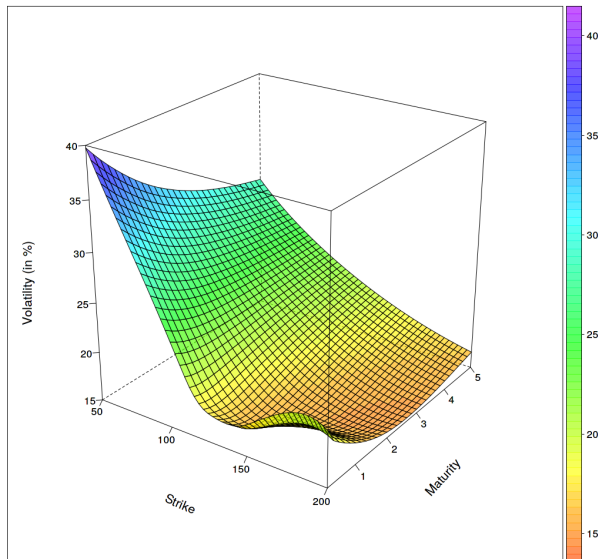
$$L(x, t + \Delta t) = \sigma_{LV}(x, t + \Delta t) \sqrt{\frac{\int_{\mathbb{R}^+} p(x, \nu, t + \Delta t) d\nu}{\int_{\mathbb{R}^+} \nu p(x, \nu, t + \Delta t) d\nu}}$$

- 3 Set $t := t + \Delta t$
- 4 If t is smaller than the final maturity goto 1

Motivation: Set-up extreme test case for the LSV calibration

- Feller condition is strongly violated with $\alpha = 0.6$
- Implied volatility surface of the Heston and the local volatility model differ significantly.
- Local Volatility: $\sigma_{LV}(x, t) \equiv 30\%$
- Heston Parameters:
 $S_0 = 100, \sqrt{\nu_0} = 24.5\%, \kappa = 1, \theta = \nu_0, \sigma^2 = 0.2, \rho = -75\%$
- Use log coordinates and modified Craig-Sneyd scheme

Calibration Example: Heston Implied Volatility Surface

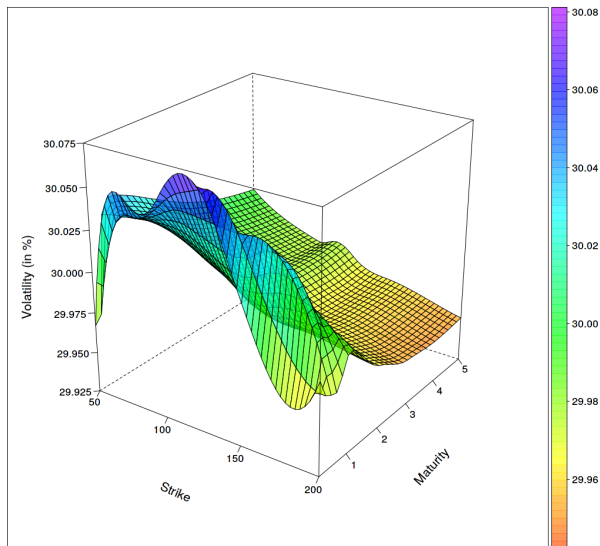


Quality of calibration is tested by the round trip error

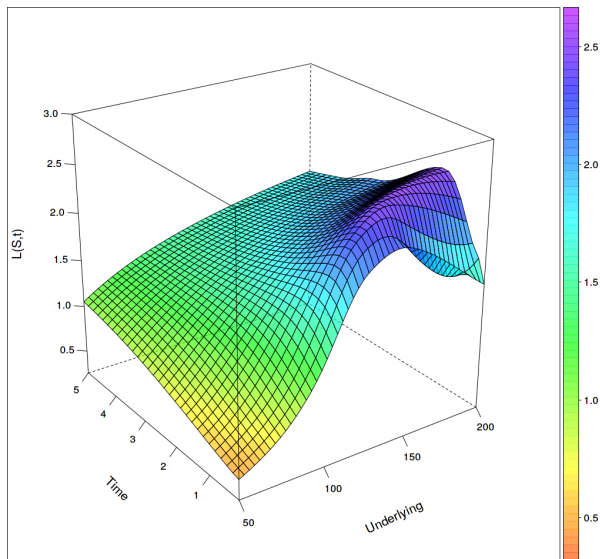
- Fokker-Planck step: Calibrate the leverage function $L(x, t)$
- Feynman-Kac step: Calculate European option prices under resulting LSV model and back out implied volatility surface
- Show differences w.r.t. expected value of

$$\sigma_{impl}(K, t) = \sigma_{LV}(S, t) = 30\%$$

Calibration Example: LSV Implied Volatility Surface



Calibration Example: Leverage Function $L(S_t, t)$



Conclusion: Heston Local Volatility in QuantLib

- ✓ Backward Feynman-Kac solver
- ✓ Forward Fokker-Planck solver
 - ✓ Zero-Flux boundary condition
 - ✓ natural and log coordinates, transformed probability density
- ✓ Non-uniform meshers are a key factor for success
- ✓ Heston Local Volatility calibration
- ✓ Round trip errors are around 5bp in vols for extreme case

Repository:

<https://github.com/jschnetm/quantlib/tree/slv/QuantLib>



William Feller.

Two singular diffusion problems.

The Annals of Mathematics, 54(1):173–182, 1951.



Vladimir Lucic.

Boundary conditions for computing densities in hybrid models via PDE methods.

Stochastics, 84(5-6):705–718, 2012.



Yu Tian, Zili Zhu, Geoffrey Lee, Fima Klebaner, and Kais Hamza.
Calibrating and Pricing with a Stochastic-Local Volatility Model.,
2014.

<http://ssrn.com/abstract=2182411>.

The views expressed in this presentation are the personal views of the speakers and do not necessarily reflect the views or policies of current or previous employers.